



Department of Electrical Engineering  
School of Science and Engineering

## EE310 Signals and Systems

### TUTORIAL 7

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#### Information:

- We use the following Fourier transform pairs:

$$\mathcal{F}\{e^{-at} u(t)\} = \frac{1}{a + j\omega},$$

$$\mathcal{F}\{u(t)\} = \frac{1}{j\omega} + \pi\delta(\omega).$$

#### Tutorial 7-1

Using the duality property of Fourier transform, determine the inverse Fourier transform of  $X(j\omega) = u(\omega)$ .

#### Tutorial 7-2

The following differential equation relates the output  $y(t)$  of causal continuous LTI system to the input  $x(t)$

$$\frac{dy(t)}{dt} + 3y(t) = x(t)$$

- Determine the frequency response  $H(j\omega) = Y(j\omega)/X(j\omega)$  and sketch the magnitude of  $H(j\omega)$ .
- If  $x(t) = e^{-t}u(t)$ , determine  $Y(j\omega)$  and  $y(t)$ .

#### Tutorial 7-3

A casual and stable LTI system has the frequency response

$$H(j\omega) = \frac{j\omega + 4}{6 - \omega^2 + 5j\omega}$$

and frequency domain description:

$$Y(j\omega) = H(j\omega) X(j\omega)$$

- Using the property:

$$\mathcal{F}\left\{\frac{d^k z(t)}{dt^k}\right\} = (j\omega)^k Z(j\omega), \quad k = 0, 1, 2, \dots$$

where

$$\mathcal{F}\{z(t)\} = Z(j\omega),$$

find the **differential equation** relating the input  $x(t)$  (and its derivatives) and output  $y(t)$  (and its derivatives) of the system with frequency response  $H(j\omega)$ .

- Find the **partial fraction expansion** of  $H(j\omega)$ .
- Determine the **impulse response**  $h(t)$  corresponding to frequency response  $H(j\omega)$ .