

# **Machine Learning**

**EE514 - CS535** 

Dimensionality Reduction: Feature Selection and Feature Extraction (PCA)



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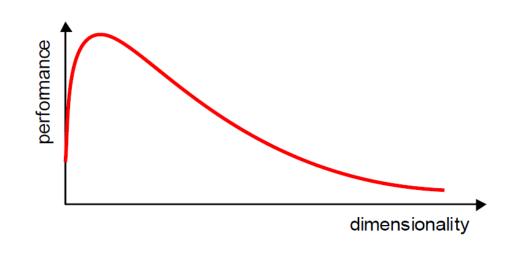
## **Outline**

- Dimensionality Reduction
- Feature Selection
- Feature Extraction PCA



## Why?

- Increasing the number of inputs or features does not always improve accuracy of classification.
- Performance of classifier may degrade with the inclusion of irrelevant or redundant features.
- Curse of dimensionality; "Intrinsic" dimensionality of the data may be smaller than the actual size of the data.



### **Benefits:**

- Improve the classification performance.
- Improve learning efficiency and enable faster classification.
- Better understanding of the underlying process mapping inputs to output.



#### **Feature Selection and Feature Extraction:**

Given a set of features, reduce the number of features such that "the learning ability of the classifier" is maximized.

$$\mathbf{x} = [x_1, x_2, \dots, x_d]$$

### **Feature Selection:**

Select a subset of the existing features.

$$\mathbf{x} = [x_1, x_2, \dots, x_d]$$

$$\mathbf{z} = [x_{i_1}, x_{i_2}, \dots, x_{i_k}]$$

### **Feature Extraction:**

Transform existing features to obtain a set of new features using some mapping function.

$$\mathbf{x} = [x_1, x_2, \dots, x_d]$$

$$\mathbf{z} = f(\mathbf{x})$$

$$\mathbf{z} = [z_1, z_2, \dots, z_k]$$



#### **Feature Selection:**

Select a subset of the existing features.

$$\mathbf{x} = [x_1, x_2, \dots, x_d]$$

$$\mathbf{z} = [x_{i_1}, x_{i_2}, \dots, x_{i_k}]$$

Select the features in the subset that either improves classification accuracy or maintain same accuracy.

How many subsets do we have?

How do we choose this subset?



#### **Feature Selection:**

## **Example:**

$$\mathbf{x} = \begin{bmatrix} x_1, x_2, x_3, x_4, x_5 \end{bmatrix} \ y$$
 $\begin{bmatrix} 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 & 0 & 1 \\ 1 & 1 & 0 & 1 & 0 & 1 \end{bmatrix}$ 

- Five Boolean features
- $y = x_1 (or) x_2$
- $x_3 = (not) x_2$
- $x_4 = (not) x_5$

Optimal subset:

$$\{x_1, x_2\}$$
 or  $\{x_1, x_3\}$ 

Optimization in space of all feature subsets would have

 $2^d$  possibilities

Can't search over all possibilities and therefore we rely on heuristic methods.

<sup>\*</sup> Source: A tutorial on genomics by Yu (2004).

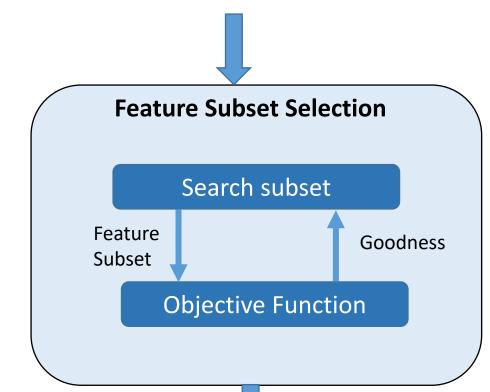


Data set:

### **Feature Selection:**

## How do we choose this subset?

- $D = \{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \dots, (\mathbf{x_n}, y_n)\} \subseteq \mathcal{X}^d \times \mathcal{Y}$
- Feature selection can be considered as an optimization problem that involves
  - Searching of the space of possible feature subsets
  - Choose the subset that is optimal or near-optimal with respect to some objective function
- Filter Methods (unsupervised method)
  - Evaluation is independent of the learning algorithm
  - Consider the input only and select the subset that has the most information
- Wrapper Methods (supervised method)
  - evaluation is carried out using model selection the machine learning algorithm
  - Train on selected subset and estimate error on validation dataset



$$D = \{(\mathbf{z_1}, y_1), (\mathbf{z_2}, y_2), \dots, (\mathbf{z_n}, y_n)\} \subseteq \mathcal{X}^k \times \mathcal{Y}$$

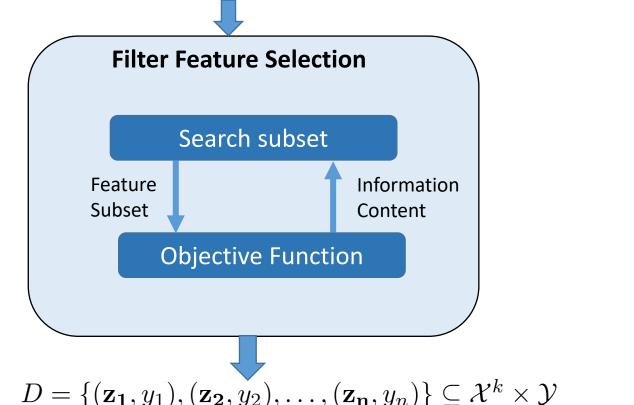
$$\mathbf{z} = [x_{i_1}, x_{i_2}, \dots, x_{i_k}]$$

#### **Feature Selection:**

#### How do we choose this subset?

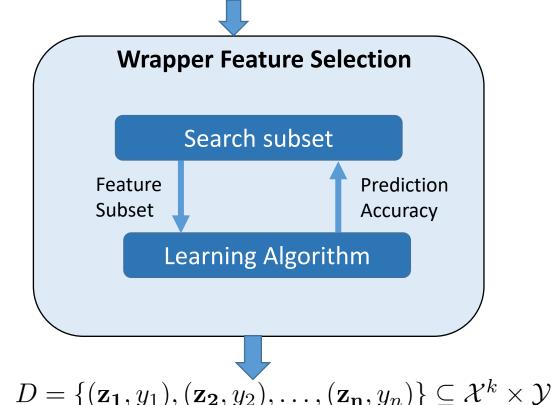
#### Filter Methods

$$D = \{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \dots, (\mathbf{x_n}, y_n)\} \subseteq \mathcal{X}^d \times \mathcal{Y}$$



### Wrapper Methods

$$D = \{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \dots, (\mathbf{x_n}, y_n)\} \subseteq \mathcal{X}^d \times \mathcal{Y}$$





### **Feature Selection:**

### **Filters Method:**

- Univariate Methods
  - Treats each feature independently of other features
- Calculate score of each feature against the label using the following metrics:
  - Pearson correlation coefficient
  - Mutual Information
  - F-score
  - Chi-square
  - Signal-to-noise ratio (SNR), etc.
- Rank features with respect to the score
- Select the top k-ranked features (k is selected by the user)



## **Feature Selection:**

## <u>Filters Method – Ranking Metrics:</u>

- Pearson correlation coefficient (measure of linear dependence)

Denote feature values by a vector  $\mathbf{a} \in \mathbf{R}^n$  (Note n is the number of points).

Denote labels by a vector  $\mathbf{y} = [y_1, y_2, \dots, y_n]$ .

Define Pearson correlation coefficient as

$$\rho = \frac{\tilde{\mathbf{a}}^T \tilde{\mathbf{y}}}{\|\tilde{\mathbf{a}}\|_2 \tilde{\mathbf{y}}\|_2}, \quad |\rho| \le 1$$

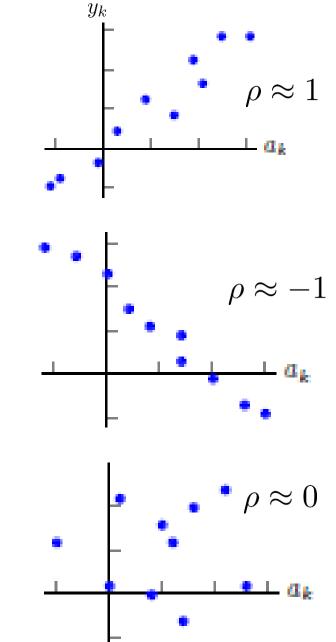
Here

$$\tilde{\mathbf{a}} = \mathbf{a} - \operatorname{avg}(\mathbf{a})\mathbf{1}$$

is a demeaned vector and is obtined by subtracting mean of a vector from it.

- Signal-to-noise ratio (SNR)

$$SNR = \frac{avg(\mathbf{a}) - avg(\mathbf{y})}{std(\mathbf{a}) - std(\mathbf{y})},$$





where std denotes the standard deviation of the vector.

#### **Feature Selection:**

## **Wrappers Method:**

- Forward Search Feature Subset Selection Algorithm (Super intuitive)
  - Start with empty set as feature subset
  - Try adding one feature from the remaining features to the subset
  - Estimate classification or regression error for adding each feature
  - Add feature to the subset that gives max improvement
- Backward Search Feature Subset Selection Algorithm (Super intuitive)
  - Start with full feature set as subset
  - Try removing one feature from the subset
  - Estimate classification or regression error for removing each feature
  - Remove/drop the feature that gives minimal impact on error or reduces the error



## **Outline**

- Dimensionality Reduction
- Feature Selection
- Feature Extraction PCA



### **Feature Extraction:**

Transform existing features to obtain a set of new features using some mapping function.

$$\mathbf{x} = [x_1, x_2, \dots, x_d]$$

$$\mathbf{z} = f(\mathbf{x})$$

$$\mathbf{z} = [z_1, z_2, \dots, z_k]$$

- The mapping function z=f(x) can be linear or non-linear.
- Can be interpreted as projection or mapping of the data in the higher dimensional space to the lower dimensional space.
- Mathematically, we want to find an optimum mapping z=f(x) that preserves the desired information as much as possible.



### **Feature Extraction:**

### <u>Idea:</u>

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- Finding optimum mapping is equivalent to optimizing an objective function.
- We use different objective functions in different methods;
  - Minimize Information Loss: Mapping that represent the data as accurately as possible in the lower-dimensional space, e.g., Principal Components Analysis (PCA).
  - Maximize Discriminatory Information: Mapping that best discriminates the data in the lower-dimensional space, e.g., Linear Discriminant Analysis (LDA).
- Here we focus on PCA, that is, a linear mapping.
- Why Linear: Simpler to Compute and Analytically Tractable.

## **Feature Extraction - Principal Component Analysis:**

- Given features in d-dimensional space
- Project into lower dimensional space using the following linear transformation

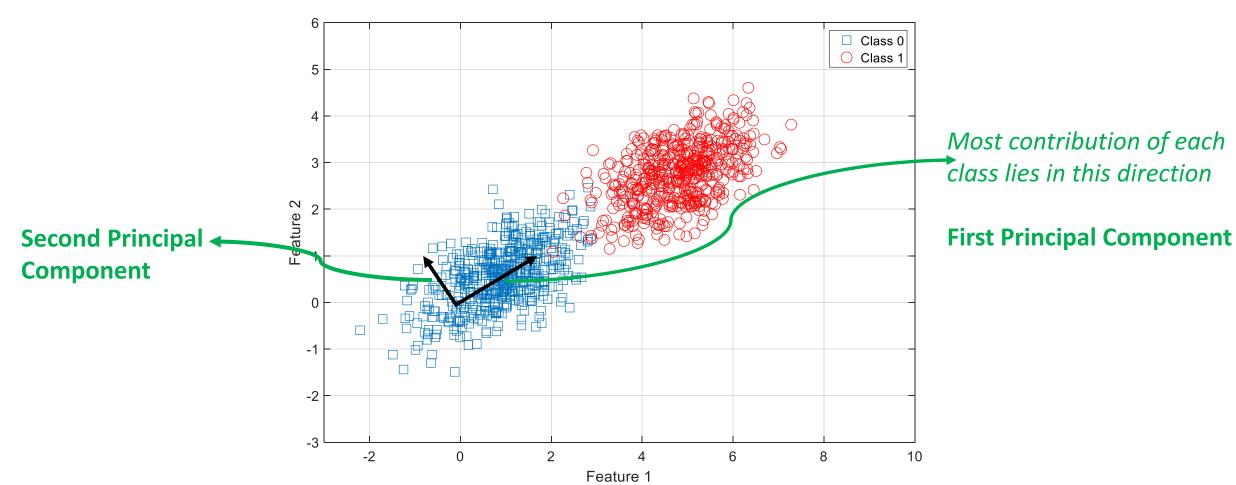
$$\mathbf{z} = \mathbf{W}^T \mathbf{x}$$

- For example (can you tell me size of matrix W for the following cases),
  - find best planar approximation to 4D data
  - find best planar approximation to 100D data
- We want to find this mapping while preserving as much information as possible, and ensuring
  - Objective 1: the features after mapping are uncorrelated; cannot be reduced further
  - Objective 2: the features after mapping have large variance



## **Feature Extraction - Principal Component Analysis:**

### **Geometric Intuition:**

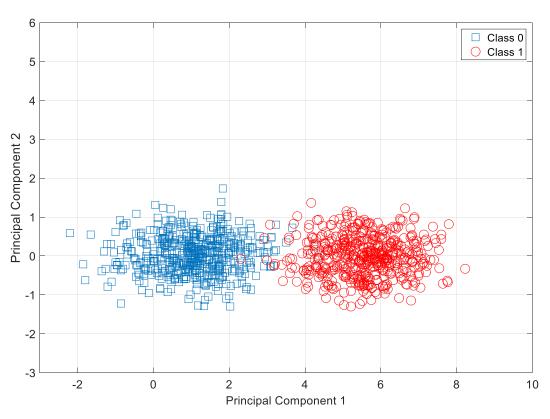




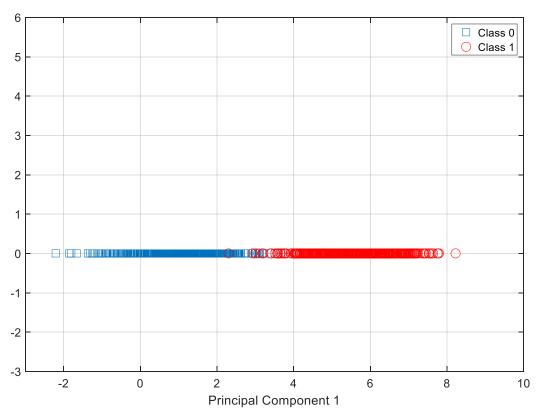
Toy Illustration in two dimensions

## **Feature Extraction - Principal Component Analysis:**

#### **Geometric Intuition:**



Change of coordinates: Linear combinations of features



Ignoring the Second Component/Feature



## **Feature Extraction - Principal Component Analysis:**

#### **Mathematical Formulation:**

We have n feature vectors of the form  $\mathbf{x} \in \mathbf{R}^d$ .

Note d represents the number of features.

In PCA, we want to represent  $\mathbf{x}$  in a new space of lower dimensionality using only k basis vectors (k < N), that is,

$$\hat{\mathbf{x}} = \sum_{i=1}^{k} z_i \mathbf{v}_i$$

such that

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$$\|\mathbf{x} - \hat{\mathbf{x}}\|_2$$

is minimized.

Here  $\mathbf{v}_i \in \mathbf{R}^d$  for i = 1, 2, ..., k represent the k number of orthogonal vectors that form the basis, referred to as principal components, of the subspace of dimensionality=k.

## **Feature Extraction - Principal Component Analysis:**

#### **Mathematical Formulation:**

How do we find the basis vectors  $\mathbf{v}_i \in \mathbf{R}^d$  for  $i = 1, 2, \dots, k$ ?

### **Steps to find Principal Components:**

We have n feature vectors  $\mathbf{x}_i \in \mathbf{R}^d$ ,  $i = 1, 2, \dots, n$ .

### **Step 1: Compute Sample Mean:**

Sample mean (note summtion over the number of feature vectors n)

$$\overline{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{x}_i$$

### **Step 2: Subtract Sample Mean:**

Subtract sample mean from each feature vector  $\mathbf{x}_i$  to obtain  $\mathbf{s}_i$ , that is,



$$\mathbf{s}_i = \mathbf{x}_i - \overline{\mathbf{x}}$$

## **Feature Extraction - Principal Component Analysis:**

### **Mathematical Formulation:**

## **Step 3: Calculate the Covariance Matrix:**

Now we have n feature vectors  $\mathbf{s}_i \in \mathbf{R}^d$ ,  $i = 1, 2, \dots, n$ .

What is special about these vectors?

Zero mean; taken along all feature vectors

Calculate the Covariance Matrix as follows

$$\Sigma = \frac{1}{n} \sum_{i=1}^{n} \mathbf{s}_i \mathbf{s}_i^T$$

This can also be expressed as

$$\Sigma = \frac{1}{n} \mathbf{S} \mathbf{S}^T$$

where

$$\mathbf{S} = [\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n]$$

How do you interpret the entries of the matrix? Spend some time and try to understand this!

For two vectors  $\mathbf{f}, \mathbf{g} \in \mathbf{R}^n$ , covariance is defined as

$$\sigma_{\mathbf{fg}} = \frac{1}{n} \sum_{i}^{n} (f_i - \operatorname{avg}(\mathbf{f})) (g_i - \operatorname{avg}(\mathbf{g}))$$



### **Feature Extraction - Principal Component Analysis:**

### **Special about the Covariance Matrix:**

The covarince matrix is symmetric, that is,  $\Sigma^T = \Sigma$ . (super easy to show)

The covarince matrix is positive semi-definite. (again, super easy)

Size of  $\Sigma$  is  $d \times d$ .

### **Step 4: Carry out Eigenvalue Decomposition of Covariance Matrix:**

Carry out eigenvalue decomposition of the covarince matrix as

$$\Sigma = \mathbf{V}\mathbf{D}\mathbf{V}^T$$

Here the matrix  $\mathbf{V} = [\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_d]$  contains d orthogonal eigenvectors  $\mathbf{v}_i \in \mathbf{R}^d$ , referred to as principal components, that serve as the basis of  $\mathbf{R}^d$ .

Here the matrix **D** is a diagonal matrix with eigenvalues denoted by  $\lambda_1, \lambda_2, \ldots, \lambda_d$ .



## **Feature Extraction - Principal Component Analysis:**

### **Step 5: Dimensionality Reduction**

We wanted to find the basis vectors  $\mathbf{v}_i \in \mathbf{R}^d$  for  $i = 1, 2, \dots, k$ .

We have  $\mathbf{v}_i \in \mathbf{R}^d$  for  $i = 1, 2, \dots, d$ .

- Q: How to select k out of d?
- A: Simple, select the ones corresponding to k largest eigenvalues.

Construct the manping matrix of size  $d \times k$  as

$$\mathbf{W} = [\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k]$$

to reduce the dimensionality of the feature space from  $\mathbf{R}^d$  to  $\mathbf{R}^k$  as

$$\mathbf{z} = \mathbf{W}^T \mathbf{x}$$



### **Feature Extraction - Principal Component Analysis:**

Using  $\mathbf{z}$ , we can go back to  $\mathbf{R}^d$  to obtain approximation of  $\mathbf{x}$  as

$$\hat{\mathbf{x}} = \sum_{i=1}^k z_i \mathbf{v}_i = \mathbf{W} \mathbf{z}$$

### **Connection with the Objectives:**

- Objective 1: the features after mapping are uncorrelated; cannot be reduced further
  - Enabled by orthogonality of the principal components
- Objective 2: the features after mapping have large variance
  - We have used covariance matrix to define the mapping and used eigenvectors with largest eigenvalues, that is, those dimensions capturing the variations in the data.
  - PCA maps the data along the directions where we have most of the variations in the data.

### **Feature Extraction - Principal Component Analysis:**

### How do we choose k?

- It depends on the amount of information, that is variance, we want to preserve in the mapping process.
- We can define a variable T to quantify this preservation of information

$$\frac{\sum_{i=1}^{k} \lambda_i}{\sum_{i=1}^{d} \lambda_i} > T$$

- T=1, when k=d; No reduction.
- T=0.8, interpreted as that 80% variation in the data has been preserved.



## **Feature Extraction - Principal Component Analysis:**

**Example:** d = 2, n = 10, k = 1

#### **Step 1: Compute sample mean:**

$$\bar{\mathbf{x}} = [1.81, 1.91]$$

 $x_1$ 

 $x_2$ 

	$\omega_Z$	_
2.5000	2.4000	$\mathbf{x}_1$
	0.7000	
2.2000	2.9000	
1.9000	2.2000	

#### **Step 2: Subtract Sample Mean:**

$$\mathbf{s}_i = \mathbf{x}_i - \overline{\mathbf{x}}$$

-1.3100 -1.2100 
$$|\mathbf{s}_2|$$

#### **Step 3: Calculate the Covariance Matrix:**

$$\mathbf{S} = [\mathbf{s}_1, \mathbf{s}_2, \dots, \mathbf{s}_n]$$

$$\Sigma = \frac{1}{n} \sum_{i=1}^{n} \mathbf{s}_{i} \mathbf{s}_{i}^{T} = \frac{1}{n} \mathbf{S} \mathbf{S}^{T}$$

$$\Sigma = \begin{bmatrix} 0.5549 & 0.5539 \\ 0.5539 & 0.6449 \end{bmatrix}$$

We have divided by n. Some authors divide by n-1. It won't change the principal components



### **Feature Extraction - Principal Component Analysis:**

## **Example:**

## **Step 4: Carry out Eigenvalue Decomposition of Covariance Matrix:**

$$\Sigma = \mathbf{V}\mathbf{D}\mathbf{V}^T$$
  $\mathbf{V} = \begin{bmatrix} -0.7352 & 0.6779 \\ 0.6779 & 0.7352 \end{bmatrix}$   $\mathbf{D} = \begin{bmatrix} 0.0442 & 0 \\ 0 & 1.1556 \end{bmatrix}$ 

## **Step 5: Dimensionality Reduction**

Use  $\mathbf{W} = [\mathbf{v}_2]$  (associated with the largest eigenvalue) to reduce the dimensionality of the feature space from  $\mathbf{R}^2$  to  $\mathbf{R}$  as

$$\mathbf{z} = \mathbf{W}^T \mathbf{x}$$



7

0.8536

3.6233

2.9054

4.3069

3.5441

2.5320

1.4866

2.1931

1.4073



### **Feature Extraction - Principal Component Analysis:**

#### **Practical Considerations and Limitations:**

- Data should be normalized before using PCA for dimensionality reduction.
- Usually, we normalize every feature by subtracting mean of that feature followed by dividing with standard deviation of the feature.
- The covariance matrix of the reduced feature is projection along orthogonal components (directions) and therefore features are uncorrelated to each other. In other words, PCA decorrelates the features.

#### - Limitation:

- PCA does not consider the separation of data with respect to class label and therefore we do not have a guarantee the mapping of the data along dimensions of maximum variance results in the new features good enough for class discrimination.

<u>Solution:</u> Linear Discriminant Analysis (LDA) – Find mapping directions along which the classes are best separated.



# Feedback: Questions or Comments?

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